

# Bayesian inference for population prediction of individuals without health insurance in Florida

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# Outline

- ▶ Motivation
- ▶ Description of the Behavioral Risk Factor Surveillance System, BRFSS
- ▶ Description of posterior predictive distribution under informative/non-informative sampling
- ▶ Selection bias
- ▶ Inference for proportions of individuals without the health insurance
- ▶ Variation of maps

# Motivation:

Interest:

1. Inference for the county-level proportions of persons without health insurance in FL, using the 2010 Behavioral Risk Factor Surveillance System, BRFSS.
2. Display the variation of maps

## 2010 BRFSS: Survey description

- ▶ The largest on-going telephone based survey; administered by the Centers for Disease Control and Prevention.
- ▶ Collect data on individual risk behaviors and preventive health practices for the adult population(18 years of age and older); collects state-specific data
  - ▶ ex: alcohol/cigarette consumption, general health status, health insurance,
- ▶ Uses a disproportionate stratified sample (DSS) design.
- ▶ In FL, 63 out of 67 counties were sampled.
- ▶ No cell phones for 2010.

# Examples of observed data

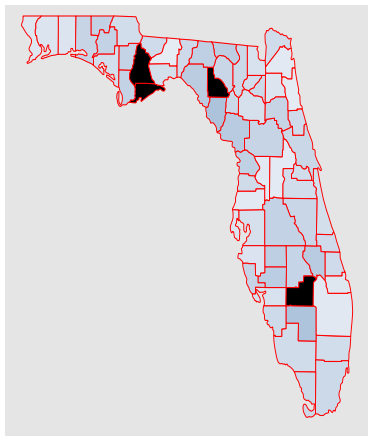


Figure: Observed: All races

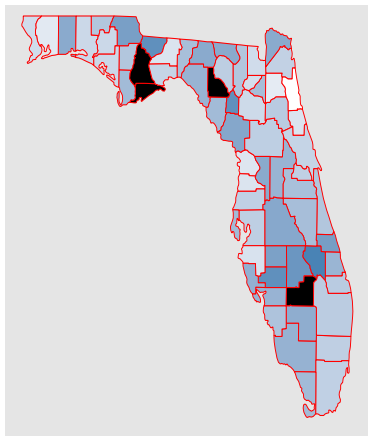


Figure: Observed: Hispanics

white=having insurance,  
blue=not having insurance

# Complication

1. Small or non-existent number of observations for some sub-population groups in certain geographical areas.
2. Possible presence of selection bias in the sample

# Model specification for the BRFSS data

$$\begin{aligned}P(Y_{ik\ell} = 1|\theta_{ik}) &= \theta_{ik} \\ \text{logit}(\theta_{ik}) &= \mathbf{X}'_k \boldsymbol{\beta} + \nu_i \\ \nu_i &\sim N(0, \sigma_\nu^2)\end{aligned}$$

- ▶  $Y_{ik\ell} = 1$  : not having insurance,  $Y_{ik\ell} = 0$  : having insurance
- ▶  $i = 1, \dots, M$ : county
- ▶  $k = 1, \dots, K$ : population class (9 age groups  $\times$  3 races  $\times$  2 genders )
- ▶  $\ell = 1, \dots, N_{ik}$ : units in county  $i$  and group  $k$
- ▶  $N_{ik}$  = population size in  $i$ th county and  $k$ th group
- ▶  $\mathbf{X}'_k$  = vector of indicators for group  $k$ .
- ▶  $p(\boldsymbol{\beta}) = \text{const on } (-\infty, \infty)$  Gelman et al.(2004)
- ▶  $p(\sigma_\nu^2) = \text{const on } (0, \infty)$

# Model Evaluation

## Model fit

- ▶ Bayes residual plots
- ▶ QQ plots
- ▶ Bayesian tests: Partial posterior predictive p-values, Bayarri and Berger(2002)

## Predictions

- ▶ Cross-validation to simulate finite population inference
  - ▶ Use  $100(1-p)\%$  of observed data to make predictions for the  $100*p\%$  that were “held-out”



# Posterior predictive distribution with non-informative sampling

Use posterior predictive distribution to make inference for the remaining non-sampled units

Under the non-informative sampling, i.e. independence between the probability of selecting a person and the response:

- ▶  $\mathbf{Y}_s$  = sampled units,  $\mathbf{Y}_{ns}$  = non-sampled units
- ▶  $\mathbf{Y}_{ns} \perp\!\!\!\perp \mathbf{Y}_s | \boldsymbol{\theta}, \mathbf{X}$
- ▶  $f(\mathbf{Y}_{ns} | \mathbf{Y}_s, \mathbf{X}) = \int g(\mathbf{Y}_{ns} | \mathbf{Y}_s, \mathbf{X}, \boldsymbol{\theta}) p(\boldsymbol{\theta} | \mathbf{Y}_s, \mathbf{X}) d\boldsymbol{\theta}$   
 $= \int g(\mathbf{Y}_{ns} | \boldsymbol{\theta}, \mathbf{X}) p(\boldsymbol{\theta} | \mathbf{Y}_s, \mathbf{X}) d\boldsymbol{\theta}$
- ▶  $p(\boldsymbol{\theta} | \mathbf{Y}_s, \mathbf{X}) \propto L(\boldsymbol{\theta} | \mathbf{Y}_s, \mathbf{X}) p(\boldsymbol{\theta} | \boldsymbol{\beta}, \sigma_\nu^2) p(\boldsymbol{\beta}, \sigma_\nu^2)$ : posterior distribution
  - ▶  $\boldsymbol{\theta}$  = a vector of model parameters
  - ▶  $(\boldsymbol{\beta}, \sigma_\nu^2)$  = a vector of hyperparameters

# Under informative sampling

- ▶ Selection probabilities are related to the outcome variables.
- ▶ The observed outcomes may not be representative of the population outcomes.
- ▶ May cause bias for inferences about the finite population parameters.

# Selection bias

Let  $\mathbf{I} = (I_1, \dots, I_N)$ ,

$I_i = 1$  if  $i \in s$ ,  $I_i = 0$  if  $i \notin s$ ,  $s = \text{sample}$

The posterior predictive distribution with  $\mathbf{I}$



$$f(\mathbf{Y}_{ns} | \mathbf{Y}_s, \mathbf{X}, \boldsymbol{\theta}, \mathbf{I}) \propto g(\mathbf{Y}_{ns} | \boldsymbol{\theta}, \mathbf{X}) p(\mathbf{I} | \mathbf{Y}, \mathbf{X}, \boldsymbol{\theta}) \quad (1)$$

Note:

- ▶  $p(\mathbf{I} | \mathbf{X}, \mathbf{Y}, \boldsymbol{\theta}) \neq p(\mathbf{I} | \mathbf{X}, \boldsymbol{\theta})$  i.e. selection bias.
- ▶ Selection information only comes from the sampled units.

## Procedure: Ha and Sedransk(2015)

1. Pfeffermann and Sverchkov (2009):

$$p(\mathbf{I}|\mathbf{Y}, \mathbf{X}, \theta) = p(\mathbf{I}|\mathbf{Y}, \mathbf{X}) = \prod_k f_1(\mathbf{I}_k|\mathbf{Y}, \mathbf{X}_k)$$

2. Using the Poisson sampling approximation, Chambers et. al.(1998)

$$p(\mathbf{I}|\mathbf{Y}, \mathbf{X})$$

$$= \prod_{i=1}^M \prod_{k=1}^K \left\{ \prod_{\ell \in s_{ik}} P(I_{ik\ell} = 1|\mathbf{Y}, \mathbf{X}_k) \right\} \left\{ \prod_{\ell \notin s_{ik}} (1 - P(I_{ik\ell} = 1|\mathbf{Y}, \mathbf{X}_k)) \right\}$$

3.  $P(I_{ik\ell} = 1|\mathbf{Y}, \mathbf{X}_k) = E_U(\pi_{ik\ell}|\mathbf{Y}, \mathbf{X}_k) = \{E_s(w_{ik\ell}|\mathbf{Y}, \mathbf{X}_k)\}^{-1}$ ,  
Pfeffermann and Sverchkov (2009),

- ▶  $\pi_{ik\ell}$  = probability of unit selected
- ▶  $w_{ik\ell} = 1/\pi_{ik\ell}$

# Posterior predictive distribution with inclusion probability

- ▶  $g(\mathbf{Y}_{ns} | \mathbf{Y}_s, \mathbf{X}, \boldsymbol{\theta}, \mathbf{I}) \approx g(\mathbf{Y}_{ns} | \boldsymbol{\theta}, \mathbf{X}) \times \prod_{i=1}^M \prod_{k=1}^K (1 - a_k)^{M_{ik1}} (1 - b_k)^{M_{ik0}},$ 
  - ▶  $a_k = \frac{1}{\bar{w}_{k,y0}}, b_k = \frac{1}{\bar{w}_{k,y1}}$
  - ▶  $\bar{w}_{k,y0}$  = average of inverse probability of selected units for class  $k$  with response  $Y_{ik\ell} = 0$
  - ▶  $\bar{w}_{k,y1}$  = average of inverse probability of selected units for class  $k$  with response  $Y_{ik\ell} = 1$
  - ▶  $M_{ik1}$  : # non-sampled units with  $Y_{ik\ell} = 1$
  - ▶  $M_{ik0}$  : # non-sampled units with  $Y_{ik\ell} = 0$
  - ▶  $M_{ik1} + M_{ik0} = N_{ik} - n_{ik}$
- ▶ Use rejection sampling algorithm to obtain  $g(\mathbf{Y}_{ns} | \cdot)$ , Robert, C. and Casella, G. (2004)

In our data set,  $0.96 \leq (1 - a_k)/(1 - b_k) \leq 1.01$  with 43 of the 54  $K$  groups.

- ▶ *No substantial selection bias.*

# Comparison between prediction to observation

## County comparison

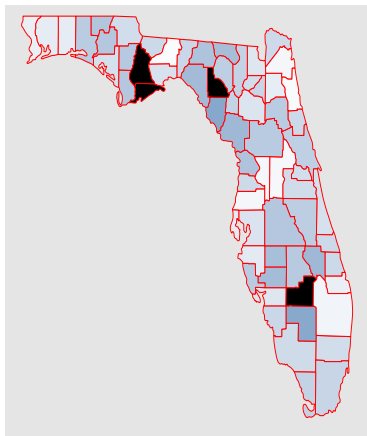


Figure: Observed: All races

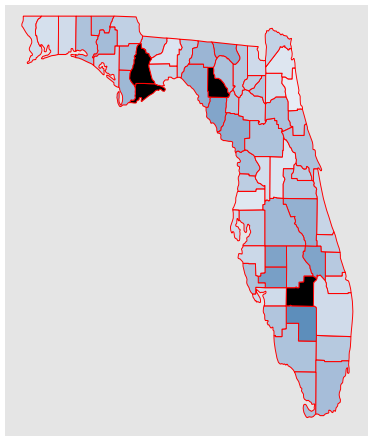


Figure: Predicted: All races

# Comparison between prediction to observation

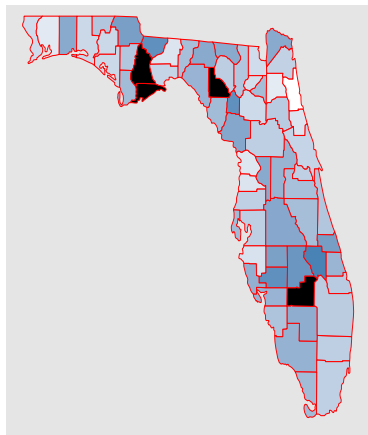


Figure: Observed: Hispanics

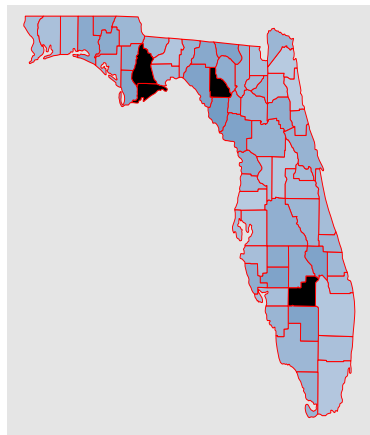


Figure: Predicted: Hispanics

# Comparison between races

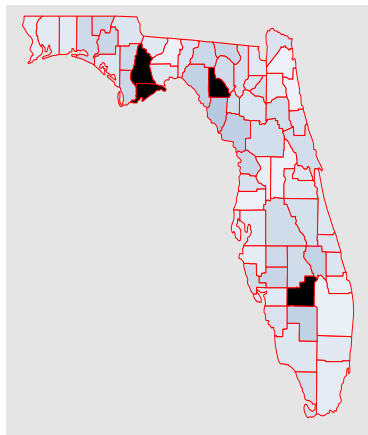


Figure: Predicted: Whites

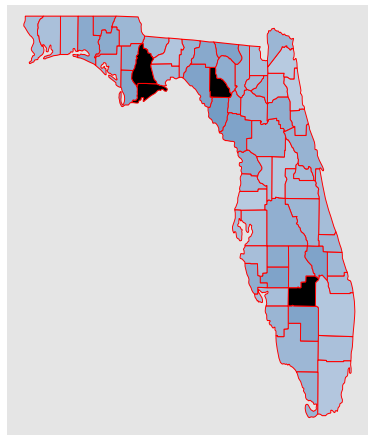


Figure: Predicted: Hispanics



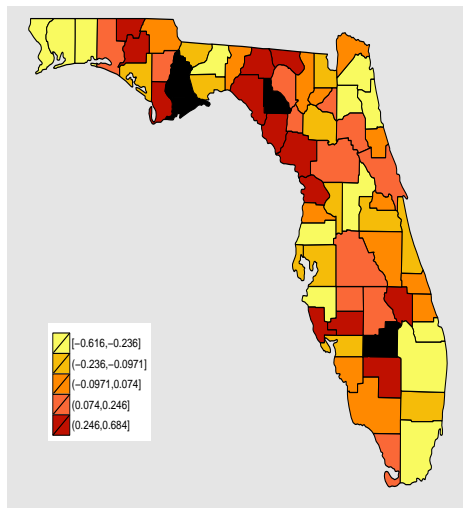
# Variation of maps

Objective: Assess the variation of the entire map as a unit rather than expressing the variation separately for each geographic unit.

- ▶ Produce a map, based on each MCMC replicate.
- ▶ Analyze variations from a set of maps

Illustrate variation between the counties from  $\nu_i$ , the county-level random effect.

# Mean choropleth map of random effect



- ▶ Posterior means of county-level random effects,  $\nu_i$ , are partitioned into quintiles
- ▶ Each quintile is color coded

Figure: Mean map of  $\hat{\nu}_i$

# Besag Method, Besag et al (1995)

- ▶ Provide  $100(1 - a)\%$  regions for each of  $\nu_i$ :  
 $\nu_i(L) < \nu_i < \nu_i(U)$
  - ▶ Construct lower choropleth map of  $\nu_i(L)$  and  $\nu_i(U)$
1. Denote the posterior MCMC sample by  
 $\{\nu_i^{(t)} : i = 1, \dots, M, t = 1, \dots, T\}$
  2. Order  $\{\nu_i^{(t)} : t = 1, \dots, T\}$  separately for each  $i$  to obtain order statistics  $x_i^{[t]}$  and ranks  $r_i^{(t)}$
  3. For fixed  $k \in \{1, \dots, T\}$ , let  $t^*$  be the smallest integer such that  $x_i^{[T+1-t^*]} \leq x_i^{(t)} \leq x_i^{[t^*]}$ , for all  $i$ , for at least  $k$  values of  $t$
  4.  $t^* = k$ th order statistic from the set  
 $a^{(t)} = \max\{\max_i r_i^{(t)}, T + 1 - \min_i r_i^{(t)}\}, t = 1, \dots, T$ , i.e.  $t^* = a^{[k]}$
  5. Then,  $\{[x_i^{[T+1-t^*]}, x_i^{[t^*]}] : i = 1, \dots, M\}$  are a set of simultaneous credible regions containing at least  $100k/T\%$  of the distribution

# Lower and Upper maps

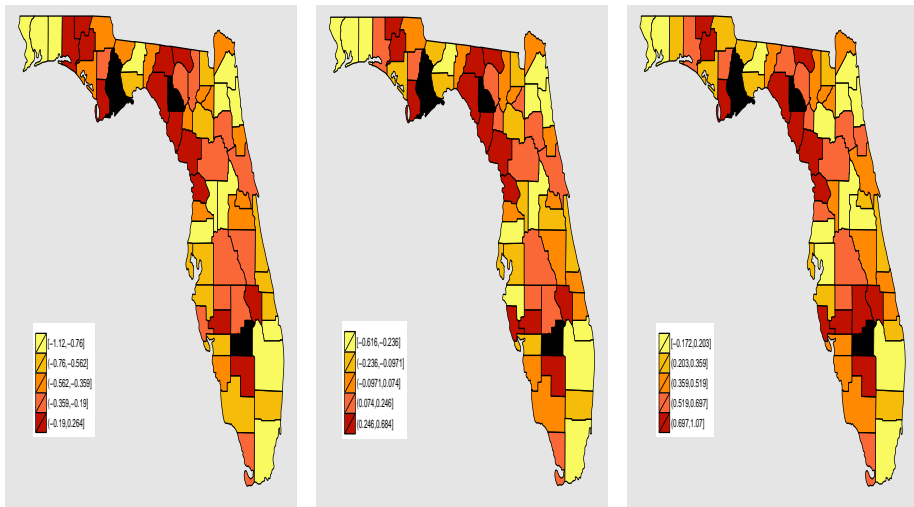


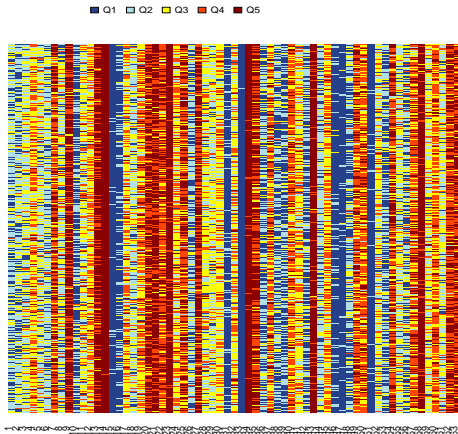
Figure: 90 % Lower, Mean, 90% Upper

# Variation in Choropleth map

Goal: Illustrate the uncertainty of the choropleth maps.

- ▶ Use  $T = 1000$  MCMC replications of  $\nu_i$
- ▶ Each replication can be used to produce a choropleth map.
- ▶ Each quintile is color coded.
- ▶ For each replication, the value of  $i$ th county is color-coded according to its quintile.

# Heat map



- ▶ Rows: replicates, columns: counties
- ▶ Variation in maps is evaluated by color changes

# Summary

- ▶ Present a method for posterior predictive inference that includes selection information for sampled units
- ▶ Illustrate variation of maps

# Reference

1. Chambers, R. L., Dorfman, A. and Wang, W. (1998). Limited Information Likelihood Analysis of Survey Data. *Journal of the Royal Statistical Society*, **60**, 397-411  
Bayesian benchmarking with application to small area estimation *Test* **20** 574-588
2. Gelman, A., Carlin, J. Stern, H. and Rubin, D. (2004), *Bayesian Data Analysis*. Chapman and Hall/ CRC, New York, NY.
3. Pfeiffermann, D. and Sverchkov, M. (2009) Inference under Informative Sampling *Sample Surveys: Inference and Analysis*, **29B**, 455-487
4. Robert, C. and Casella, G. (2004), *Monte Carlo Statistical Methods*, Springer, New York, NY.