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 CAR(1) DistributionsDongchu Sun, Robert K. Tsutakawa, and Paul Speckman

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# Posterior distribution of hierarchical models using CAR(1) distributions 

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Summary
We examine properties of the $\operatorname{CAR}(1)$ modelFwhich is commonly used to represent regional effects in Bayesian analyses of mortality rates. We consider a Bayesian hierarchical linear mixed model where the fixed effects have a vague prior such as a constant prior and the random effect follows a class of CAR(1) models including those whose joint prior distribution of the regional effects is improper. We give sufficient conditions for the existence of the posterior distribution of the fixed and random effects and variance components. We then prove the necessity of the conditions and give a one-way analysis of variance example where the posterior may or may not exist. Finally F we extend the result to the generalised linear mixed model $\Gamma$ which includes as a special case the Poisson log-linear model commonly used in disease mapping.

Some key words: Partially informative normal distribution; Spatial correlation; Gibbs sampling; Poisson distribution; Multivariate normal; Linear mixed model.

## 1. Introduction

This paper considers the propriety of the posterior distribution for the general mixed linear model and generalised mixed linear model when the random effects are represented by the conditional autoregressive modelor CAR(1) Гintroduced by Besag (1974). CAR(1) is currently one of the most important and widely used models to represent spatial correlations in disease mapping (Clayton \& KaldorГ1987; Cressie \& ChanГ1989; MarshallГ1991; BernardinelliГClayton \& MontomoliГ1995; and Waller et al.Г1997).

The recent popularity of $\operatorname{CAR}(1)$ is primarily due to the ease with which it may be implemented in the Gibbs sampler (Gelfand \& SmithГ1990). HoweverГsuch convenience may lead to overlooking the possibility that the posterior distribution may fail to exist when the joint distribution under $\operatorname{CAR}(1)$ is improper.

The use of the CAR(1) model to represent spatial effects may be illustrated by a log-linear model in mortality analysis. For a given target population of size $m \Gamma$ let $Y$ denote the frequency of the deaths due to some specific cause $\Gamma$ such as lung cancer $\Gamma$ during some fixed time period. Conditionally on a population parameter $p \Gamma$ assume that $Y$ has a Poisson distribution with mean $m p$ Гwhere $p$ may be interpreted as the rate per individual. The target populations are typically cross-classified by demographic variables such as ageГsex and geographic region. The dependence of $p$ on such covariates can be represented by a log-linear model for $p$ having the form

$$
\begin{equation*}
V=X_{1} \theta+X_{2} Z+e \tag{1}
\end{equation*}
$$

where $V$ is a vector of the set $\log (p)$ associated with the target populations $\Gamma \theta$ is
a vector of fixed effects $\Gamma Z$ is a vector of random regional effects $\Gamma$ and $X_{1}$ and $X_{2}$ are design matrices. The vector $e$ represents unexplained random effects and is often omitted in the literature. Related models may be found in Tsutakawa (1988) and Marshall (1991).

In practiceГtwo forms of the CAR(1) model are widely used to represent spatial effects. Let $Z=\left(Z_{1}, \cdots, Z_{q}\right)^{\prime}$ denote the real-valued regional effects of $q$ regions $\Gamma$ $\Lambda_{i}$ the set of regions that are geographically adjacent to region $i$ and $d_{i}$ the number of regions in $\Lambda_{i} \Gamma i=1, \cdots, q$. In Model $1 \Gamma$ the conditional distribution of $Z_{i}$ given the other regional effects $Z_{-i}=\left(Z_{1}, \cdots, Z_{i-1}, Z_{i+1}, \cdots, Z_{q}\right)^{\prime}$ is assumed to be $N\left(\sum_{j \in \Lambda_{i}} Z_{j} / d_{i}, \delta_{1} / d_{i}\right)$. In Model $2 \Gamma$ the conditional distribution is assumed to be $N\left(\rho \sum_{j \in \Lambda_{i}} Z_{j}, \delta_{1}\right)$. Model 1 was proposed by Besag $\Gamma$ York $\Gamma \&$ Mollié (1991) and used by Bernardinelli \& Montomoli (1992)ГBernardinelli et al. (1995) ГWaller et al. (1997) and Ghosh et al. (1998) Tamong others. Model 2 was proposed by Clayton \& Kaldor (1987) and used by N. J. McMillan and L. M. Berliner in a National Institute of Statistical Sciences technical report. Both models are designed to account for spatial correlations among neighbouring regions.

In $\S 2$ we examine the joint distribution of the $\operatorname{CAR}(1)$ model and demonstrate that $\Gamma$ when the covariance matrix of $Z$ is not positive definite $\Gamma$ e.g. Model $1 \Gamma$ the joint distribution may be decomposed into a component which is nonsingular normal and another which has a constant density over some Euclidian spaceГimplying that the distribution is improper. We also examine properties of Models 1 and 2 and introduce a modification (Model 1A) of Model 1 which has a proper joint distribution.

The effect of such improper distributions on the posterior distribution for hier-
archical models is examined in $\S 3$. We consider the linear mixed model where the fixed effects have a uniform prior and the random effects have an arbitrary Gaussian CAR(1) distribution. We give sufficient conditions for the linear effects and variance components to have a proper posterior distribution. We also show the necessity of one of these conditions and provide an illustration of a balanced one-way analysis of variance model where the posterior may or may not be proper. Finally we prove the propriety of the posterior distribution for the generalised linear mixed model $\Gamma$ which includes the mortality example as a special case. Our results are closely related to these of Ghosh et al. (1998) Гwho have previously shown the existence of the posterior under Model $1 \Gamma$ and to those of Hobert \& Casella (1996) $\Gamma$ who considered the hierarchical model where the covariance matrix of the random effects is positive definite. The discussion of the CAR(1) model is also related to Hobert \& Casella's (1998) functional compatibility.

## 2. Gaussian CAR(1) model

Let $Z=\left(Z_{1}, \cdots, Z_{q}\right)^{\prime}$ be a random vector with full conditional densities

$$
\begin{equation*}
f\left(Z_{i} \mid Z_{-i}\right)=\left(\frac{a_{i}}{2 \pi \delta_{1}}\right)^{\frac{1}{2}} \exp \left\{-\frac{a_{i}}{2 \delta_{1}}\left(Z_{i}-\sum_{j \neq i}^{q} \beta_{i j} Z_{j}\right)^{2}\right\} \tag{2}
\end{equation*}
$$

$i=1, \cdots, q$. Let $B$ be the $q \times q$ matrix with diagonal elements $a_{i}$ and $i j$ th off-diagonal element $-a_{i} \beta_{i j}$. Besag (1974) proved that $\Gamma$ if $B$ is symmetric and positive definite $\Gamma$ these conditional distributions lead to the joint probability density function of $Z \Gamma$

$$
\begin{equation*}
f(Z)=\left(2 \pi \delta_{1}\right)^{-q / 2}|B|^{1 / 2} \exp \left\{-\frac{1}{2 \delta_{1}} Z^{\prime} B Z\right\} . \tag{3}
\end{equation*}
$$

In this case $\Gamma Z$ is multivariate normal with mean $0_{q}$ and covariance matrix $\delta_{1} B^{-1}$. When $B$ is nonnegative definite but not positive definite $\Gamma$ the relationship between
(2) and the joint distribution of $Z$ is less clear. In this case we will call the joint distribution a partially informative normal distribution and represent the density by

$$
\begin{equation*}
f(Z) \propto \delta_{1}^{-q / 2} \exp \left\{-\frac{1}{2 \delta_{1}} Z^{\prime} B Z\right\} \tag{4}
\end{equation*}
$$

We first note that $Z$ cannot have a singular normal distribution that is consistent with (2). If $Z$ has a singular normal distribution $\Gamma Z$ is nonsingular normal over some hyperplane $\Gamma$ so there exists at least one $Z_{i}$ such that the conditional distribution of $Z_{i}$ Гgiven $Z_{-i}$ Гis degenerate $\Gamma$ contradicting (2).

Suppose $B$ is singular nonnegative definite with rank $r$. Then there exists an orthogonal matrix $\Gamma$ such that $\Lambda=\Gamma^{\prime} B \Gamma=\operatorname{diag}\left(\lambda_{1}, \cdots, \lambda_{r}, 0, \cdots, 0\right)$, where $\lambda_{i}>0 \Gamma$ $i=1, \cdots, r<q$. Let $X=\Gamma^{\prime} Z$. Since $B=\Gamma \Lambda \Gamma^{\prime}, Z^{\prime} B Z=X^{\prime} \Lambda X=\sum_{i=1}^{r} \lambda_{i} X_{i}^{2}$. Thus $\Gamma$ if the density of $Z$ is given by (4) Гthe density of $X$ is

$$
f(X) \propto \delta_{1}^{-q / 2} \exp \left(-\frac{1}{2 \delta_{1}} \sum_{i=1}^{r} \lambda_{i} X_{i}^{2}\right)
$$

i.e. $\left(X_{1}, \cdots, X_{r}\right)$ are independent normal variables with mean 0 and variance $\delta_{1} / \lambda_{i} \Gamma$ $i=1, \cdots, r$, and $\left(X_{r+1}, \cdots, X_{q}\right)$ has density proportional to $\delta_{1}^{-(q-r) / 2}$ over a $q-r$ dimensional Euclidian space. Thus the distribution of $Z$ is improper when $B$ is singular. Note that it may be more intuitive to use $\delta_{1}^{-r / 2}$ rather than $\delta_{1}^{-q / 2}$ in (4) so that the prior of $\left(X_{1}, \cdots, X_{r}\right)$ is constant independent of $\delta_{1}$. We have chosen to follow Besag et al. (1995) and Ghosh et al. (1998) in using the exponent $q$ in (4).

We can formally relate (4) to (2) by noting that

$$
f\left(Z_{i} \mid Z_{-i}\right)=f\left(Z_{1}, \cdots, Z_{q}\right) / \int_{-\infty}^{\infty} f\left(Z_{1}, \cdots, Z_{q}\right) d Z_{i}
$$

Hobert \& Casella (1998) have called this type of relationship 'functionally compatiblel' in contrast to one which is 'compatiblel' where the integral of $f\left(Z_{1}, \cdots, Z_{q}\right)$ with
respect to $\left(Z_{1}, \cdots, Z_{q}\right)$ is finite. In the remainder of this section $\Gamma$ we will examine compatibility conditions for some important CAR(1) models.

A simple nontrivial example is given for the case $q=2$. Suppose that $f\left(Z_{1} \mid Z_{2}\right)$ is $N\left(\rho Z_{1}, 1\right)$ and $f\left(Z_{2} \mid Z_{1}\right)$ is $N\left(\rho Z_{2}, 1\right)$. In this case $B=\left(\begin{array}{cc}1 & -\rho \\ -\rho & 1\end{array}\right)$ and if $|\rho|<1$ then $Z$ is bivariate normal with mean 0 and covariance matrix $B^{-1}=\left(1-\rho^{2}\right)^{-1}\left(\begin{array}{ll}1 & \rho \\ \rho & 1\end{array}\right)$. If $\rho=1$ (the case $\rho=-1$ is similar) $\Gamma B$ is singular and the joint distribution formally becomes $f\left(Z_{1}, Z_{2}\right) \propto \exp \left\{-\frac{1}{2}\left(Z_{1}-Z_{2}\right)^{2}\right\}$, an improper distribution as in (4). Thus the conditional distributions are functionally compatible. We can generalise this example to the regional effects $\left(Z_{1}, \cdots, Z_{q}\right)^{\prime}$ by the following model.

Model 1A. Let $a_{i}=d_{i}$ and $\beta_{i j}=\rho / d_{i}$, if $j \in \Lambda_{i}$, and $0 \Gamma$ if $j \notin \Lambda_{i}$, where $|\rho|<1$; the adjacency property is assumed to be symmetric so that $i \in \Lambda_{j}$ if and only if $j \in \Lambda_{i}$. Then $a_{i} \beta_{i j}=a_{j} \beta_{j i}$ and $B$ is symmetric. Moreover $\Gamma$

$$
\begin{equation*}
B=D-\rho C \tag{5}
\end{equation*}
$$

where $D$ is the diagonal matrix with diagonal elements $d_{1}, \cdots, d_{q}$ and $C$ is the adjacency matrix $\Gamma$ with element $c_{i j}=1$, if $i$ and $j$ are adjacent $\Gamma$ and $0 \Gamma$ otherwise. The conditional distribution (2) can now be written

$$
f\left(Z_{i} \mid Z_{-i}\right)=\left(\frac{d_{i}}{2 \pi \delta_{1}}\right)^{\frac{1}{2}} \exp \left\{-\frac{d_{i}}{2 \delta_{1}}\left(Z_{i}-\rho \bar{z}_{i}\right)^{2}\right\}
$$

where $\bar{z}_{i}=d_{i}^{-1} \sum_{j \in \Lambda_{i}} Z_{j}$.
When $\rho=1$ in (5) Гwe have Model 1 proposed by Besag et al. (1991) Гand used by Carlin \& Louis (1996) ГGhosh et al. (1998) and others. In this case $\Gamma B$ cannot be positive definite since the row and column sums of $B$ will be $0_{q}$. When $\rho=0$ in (5) $\Gamma$
it reduces to the case where $Z_{1}, \cdots, Z_{n}$ are independent without spatial correlation. However Ithe variance of $Z_{i}$ is still inversely proportional to the number of neighbours $d_{i}$ Гan unlikely situation under independence.

To show that $B$ is positive definite under Model $1 \mathrm{~A} \Gamma$ we note that $\Gamma$ for any $\rho$ for which $|\rho|<1 \Gamma$ the $i$ th diagonal element is larger than the sum of the absolute values of all off diagonal elements in the $i$ th row. The following lemma Ca corollary of diagonal dominance (c.f. OrtegaГ1987Гp. 225) stated here for completenessTimplies that $B$ is positive definite. According to Besag (1974) Г $Z$ has a nonsingular normal distribution.

Lemma 1. Let $A=\left(a_{i j}\right)$ be $a q \times q$ matrix. If $a_{i i}>\sum_{j \neq i}\left|a_{i j}\right|$ for all $i$, then $A$ is positive definite.

Model 2. Let $a_{i}=1$ and $\beta_{i j}=\rho$, if $j \in \Lambda_{i}$, and 0 Гif $j \notin \Lambda_{i}$. Here $\Lambda_{i}$ is again the set of regions adjacent to region $i$. Then $\beta_{i j}=\beta_{j i}, B$ is symmetric「and

$$
\begin{equation*}
B=I_{q}-\rho C \tag{6}
\end{equation*}
$$

where $I_{q}$ is the $q \times q$ identity matrix and $C$ is the adjacency matrix. Let $\lambda_{1} \leq \lambda_{2} \leq$ $\cdots \leq \lambda_{q}$ be the ordered eigenvalues of $C$. As seen in the following lemma厂 $C$ is neither positive definite nor negative definite $\Gamma$ so that $\lambda_{1}<0$ and $\lambda_{q}>0$.

Lemma 2. Let $A=\left(a_{i j}\right)$ be an $q \times q$ nonzero symmetric matrix whose diagonal elements are all zero. Let $\lambda_{\min }$ and $\lambda_{\max }$ be the minimum and maximum eigenvalues of $A$. Then $A$ is neither positive definite nor negative definite. That is to say,

$$
\lambda_{\min }<0 \quad \text { and } \quad \lambda_{\max }>0 .
$$

Proof. Since $A$ is a nonzero matrix $\Gamma$ there is a pair $(i, j)$ such that $i<j$ and $a_{i j} \neq 0$. Let $X$ be the $q$-dimensional vector whose $i$ th and $j$ th components are 1 and other components are 0 . Clearly $X^{\prime} A X=2 a_{i j}+a_{i i}+a_{j j}=2 a_{i j}$ Гsince $a_{i i}=a_{j j}=0$. If we let $X$ be the $q$-dimensional vector whose $i$ th component is $1 \Gamma j$ th component is -1 Tand other components are 0 , we get $X^{\prime} A X=-2 a_{i j}$. The result then follows.

From Lemma 2 Twe know that $\lambda_{1}<0<\lambda_{q}$.

Theorem 1. If

$$
\begin{equation*}
\lambda_{1}^{-1}<\rho<\lambda_{q}^{-1} \tag{7}
\end{equation*}
$$

then $B$ is positive definite, and the conditional distribution (2) can be written

$$
\begin{equation*}
f\left(Z_{i} \mid Z_{-i}\right)=\left(\frac{1}{2 \pi \delta_{1}}\right)^{\frac{1}{2}} \exp \left\{-\frac{1}{2 \delta_{1}}\left(Z_{i}-\rho \sum_{i \in \Lambda_{i}} Z_{j}\right)^{2}\right\} . \tag{8}
\end{equation*}
$$

Proof. Let $\Gamma$ be an orthogonal matrix so that $C=\Gamma \operatorname{diag}\left(\lambda_{1}, \cdots, \lambda_{q}\right) \Gamma^{\prime}$. Then we have the decomposition

$$
B=\Gamma \operatorname{diag}\left(1-\rho \lambda_{1}, \cdots, 1-\rho \lambda_{q}\right) \Gamma^{\prime}
$$

The eigenvalues of $B$ are $\left(1-\rho \lambda_{1}, \cdots, 1-\rho \lambda_{q}\right)$. From (7) Гthey are all positive. This proves the first part. The second part follows immediately.

If $\rho=\lambda_{1}^{-1}$ or $\lambda_{q}^{-1}$ then $B$ will be singular and $\Gamma$ by our previous result $\Gamma$ the joint distribution of $Z$ will be improper. Moreover $\Gamma$ if $\rho<\lambda_{1}^{-1}$ or $\rho>\lambda_{q}^{-1}, B$ is no longer nonnegative definite.

Note that (8) is the model used in Clayton \& Kaldor (1987). Furthermoreएif $\rho=0$, then the model reduces to the case where $Z_{1}, \cdots, Z_{n}$ are independently and identically $N\left(0, \delta_{1}\right)$ distributed.

## 3. Existence of the Posteriors

### 3.1. Propriety of the Posterior for a Linear Mixed Model

Here and in $\S 3.2$ we examine whether or not the posterior distribution remains proper when both $\theta$ and $Z$ have noninformative priors.

Consider a general linear mixed model

$$
\begin{equation*}
V_{i}=x_{1 i}^{\prime} \theta+x_{2 i}^{\prime} Z+e_{i}, \tag{9}
\end{equation*}
$$

where $x_{1 i}$ and $x_{2 i}$ are vectors of fixed constants $\Gamma \theta$ is a vector of fixed effects $\Gamma Z$ is a vector of random effects $\Gamma$ and the $e_{i}$ are independently and identically distributed normal errors with mean 0 and variance $\delta_{0}$. For given $\delta_{1}>0, \delta_{0}>0$ and a nonnegative definite matrix $B \Gamma$ we assume that $\theta \Gamma Z \mid \delta_{1}$ and $e \mid \delta_{0}$ are independent with

$$
\begin{equation*}
w(\theta) \equiv 1 \tag{10}
\end{equation*}
$$

and $Z \mid \delta_{1}$ has the partially informative normal density (4). Assume that the variance components $\delta_{0}$ and $\delta_{1}$ are a priori independent and that $\delta_{i}$ has an inverse gamma distribution $\left(a_{i}, b_{i}\right)$ with density

$$
\begin{equation*}
g_{i}\left(\delta_{i}\right) \propto \delta_{i}^{-\left(a_{i}+1\right)} \exp \left(-b_{i} / \delta_{i}\right) \tag{11}
\end{equation*}
$$

Let $V=\left(V_{1}, \cdots, V_{n}\right)^{\prime}$ be the vector of $n$ observations $\Gamma$ and let $X_{1}=\left(x_{11}, \cdots, x_{1 n}\right)^{\prime}$ and $X_{2}=\left(x_{21}, \cdots, x_{2 n}\right)^{\prime}$ be the $n \times p$ and $n \times q$ design matrices. Denote the usual least squares estimator of $\left(\theta^{\prime}, Z^{\prime}\right)$ by $\left(\hat{\theta}^{\prime}, \hat{Z}^{\prime}\right)^{\prime}=\left(X^{\prime} X\right)^{-} X^{\prime} V \Gamma$ where $X=\left(X_{1}, X_{2}\right)$ and $\left(X^{\prime} X\right)^{-}$is a generalised inverse of $X^{\prime} X$. Let the sum of squared errors be $S S E=$ $V^{\prime}\left\{I_{n}-X\left(X^{\prime} X\right)^{-} X^{\prime}\right\} V$ which is invariant for any choice of $\left(X^{\prime} X\right)^{-}$.

Theorem 2. Consider the linear mixed model (9) with prior distribution given by (4), (10), and (11), where $B$ is nonnegative definite. Assume the following conditions.
(a) rank $\left(X_{1}\right)=p$ and $\operatorname{rank}\left(X_{2}^{\prime} R_{1} X_{2}+B\right)=q$, where $R_{1}=I_{n}-X_{1}\left(X_{1}^{\prime} X_{1}\right)^{-1} X_{1}^{\prime}$;
(b) $a_{1}>0$ and $b_{1}>0$;
(c) $n-p-q+2 a_{0}>0$ and $S S E+2 b_{0}>0$.

Then the joint posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ is proper.

Proof. First $\Gamma$ the joint posterior density of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ is proportional to

$$
\begin{equation*}
G=\delta_{0}^{-\frac{1}{2} n} \delta_{1}^{-\frac{1}{2} q} \exp \left\{-\frac{\left(V-X_{1} \theta-X_{2} Z\right)^{\prime}\left(V-X_{1} \theta-X_{2} Z\right)}{2 \delta_{0}}-\frac{Z^{\prime} B Z}{2 \delta_{1}}\right\} \prod_{i=0}^{1} g_{i}\left(\delta_{i}\right) \tag{12}
\end{equation*}
$$

Since $\left(V-X_{1} \theta-X_{2} Z\right)^{\prime}\left(V-X_{1} \theta-X_{2} Z\right)$ equals $S S E+\left(\theta-\hat{\theta}-C_{1}\right)^{\prime} X_{1}^{\prime} X_{1}\left(\theta-\hat{\theta}-C_{1}\right)$ $+(\mathrm{Z}-\hat{\mathrm{Z}})^{\prime} \mathrm{X}_{2}^{\prime} \mathrm{R}_{1} \mathrm{X}_{2}(\mathrm{Z}-\hat{\mathrm{Z}})$ Гwhere $C_{1}=\left(X_{1}^{\prime} X_{1}\right)^{-1} X_{1}^{\prime} X_{2}(\hat{Z}-Z)$, we integrate $G$ with respect to $\theta$ and get

$$
\begin{equation*}
\int G d \theta=\frac{(2 \pi)^{\frac{p}{2}}\left|X_{1}^{\prime} X_{1}\right|^{\frac{1}{2}}}{\delta_{0}^{\frac{1}{2}(n-p)} \delta_{1}^{\frac{1}{2} q}} \exp \left\{-\frac{S S E}{2 \delta_{0}}-\frac{(Z-\hat{Z})^{\prime} X_{2}^{\prime} R_{1} X_{2}(Z-\hat{Z})}{2 \delta_{0}}-\frac{Z^{\prime} B Z}{2 \delta_{1}}\right\} \prod_{i=0}^{1} g_{i}\left(\delta_{i}\right) . \tag{13}
\end{equation*}
$$

Define $R_{2}=\delta_{0}^{-1} X_{2}^{\prime} R_{1} X_{2}+\delta_{1}^{-1} B$. For any fixed $\delta_{0}, \delta_{1}>0 \Gamma R_{2}^{-1}$ exists by Assumption (a). Let $C_{2}=\delta_{0}^{-1} R_{2}^{-1} X_{2}^{\prime} R_{1} X_{2} \hat{Z}$ and $R_{3}=X_{2}^{\prime} R_{1} X_{2}-\delta_{0}^{-1} X_{2}^{\prime} R_{1} X_{2} R_{2}^{-1} X_{2}^{\prime} R_{1} X_{2}$. Then

$$
\frac{(Z-\hat{Z})^{\prime} X_{2}^{\prime} R_{1} X_{2}(Z-\hat{Z})}{\delta_{0}}+\frac{Z^{\prime} B Z}{\delta_{1}}=\left(Z-C_{2}\right)^{\prime} R_{2}\left(Z-C_{2}\right)+\frac{\hat{Z}^{\prime} R_{3} \hat{Z}}{\delta_{0}}
$$

Integrating $G$ with respect to $\theta$ and $Z \Gamma$ we get

$$
\begin{equation*}
\int_{\mathbb{R}^{q}} \int_{\mathbb{R}^{p}} G d \theta d Z=\frac{(2 \pi)^{\frac{1}{2}(p+q)}\left|X_{1}^{\prime} X_{1}\right|^{-\frac{1}{2}}}{\delta_{0}^{\frac{1}{2}(n-p)} \delta_{1}^{\frac{1}{2} q}\left|R_{2}\right|^{\frac{1}{2}}} \exp \left(-\frac{S S E+\hat{Z}^{\prime} R_{3} \hat{Z}}{2 \delta_{0}}\right) \prod_{i=0}^{1} g_{i}\left(\delta_{i}\right) . \tag{14}
\end{equation*}
$$

Since $R_{3}$ is nonnegative definite $\Gamma \hat{Z}^{\prime} R_{3} \hat{Z} \geq 0$. Note that

$$
\left|R_{2}\right|^{-\frac{1}{2}} \leq\left\{\min \left(\delta_{0}^{-1}, \delta_{1}^{-1}\right)^{q}\left|X_{2}^{\prime} R_{1} X_{2}+B\right|\right\}^{-\frac{1}{2}}<\left(\delta_{0}^{\frac{1}{2} q}+\delta_{1}^{\frac{1}{2} q}\right)\left|X_{2}^{\prime} R_{1} X_{2}+B\right|^{-\frac{1}{2}}
$$

We have

$$
\begin{equation*}
\int_{\mathbb{R}^{q}} \int_{\mathbb{R}^{p}} G d \theta d Z \leq(2 \pi)^{\frac{1}{2}(p+q)}\left|X_{1}^{\prime} X_{1}\right|^{-\frac{1}{2}}\left|X_{2}^{\prime} R_{1} X_{2}+B\right|^{-\frac{1}{2}}\left(J_{1}+J_{2}\right) \tag{15}
\end{equation*}
$$

where

$$
\begin{aligned}
& J_{1}=\frac{1}{\delta_{0}^{\frac{1}{2}(n-p-q)+a_{0}+1} \delta_{1}^{\frac{1}{2} q+a_{1}+1}} \exp \left(-\frac{2 b_{0}+S S E}{2 \delta_{0}}-\frac{b_{1}}{\delta_{1}}\right), \\
& J_{2}=\frac{1}{\delta_{0}^{\frac{1}{2}(n-p)+a_{0}+1} \delta_{1}^{a_{1}+1}} \exp \left(-\frac{2 b_{0}+S S E}{2 \delta_{0}}-\frac{b_{1}}{\delta_{1}}\right) .
\end{aligned}
$$

From Assumption (c) $\Gamma \frac{1}{2} q+a_{0}>0$. The Integral of $J_{1}$ with respect to $\left(\delta_{0}, \delta_{1}\right)$ is finite.
Also $\operatorname{CAssumption}(\mathrm{c})$ implies that $n-p+2 a_{0}>0$ and the integral of $J_{2}$ with respect to $\left(\delta_{0}, \delta_{1}\right)$ is finite. The result then follows.

Assumption (a) is equivalent to the assumption that the rank of $\left(\begin{array}{cc}X_{1}^{\prime} X_{1} & X_{1}^{\prime} X_{2} \\ X_{2}^{\prime} X_{1} & X_{2}^{\prime} X_{2}+B\end{array}\right)$
equals $p+q$. Also Assumption (a) is satisfied by either of the following conditions:
(a1) the rank of $X$ is $p+q$;
(a2) the rank of $X_{1}$ is $p$ and rank of $B$ is $q$.

Corollary 1. Consider the linear mixed model (9), whose prior distribution is given by (10) and suppose $\delta_{i}$ follows the prior (11).
(a) If Condition (a1) holds, the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ exists for any $q \times q$ nonnegative definite matrix $B$.
(b) If Condition (a2) holds, the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ exists for any $n \times q$ design matrix $X_{2}$.

Proof. From the same argument as the proof of Theorem $2 \Gamma$ (14) holds. For Part (a) Гwe know that $\left|R_{2}\right| \geq \delta_{0}^{-q}\left|X_{2}^{\prime} R_{1} X_{2}\right|$. Then

$$
\int_{\mathbb{R}^{q}} \int_{\mathbb{R}^{p}} G d \theta d Z \leq \frac{(2 \pi)^{\frac{1}{2}(p+q)}\left|X_{1}^{\prime} X_{1}\right|^{-\frac{1}{2}}\left|X_{2}^{\prime} R_{1} X_{2}\right|^{-\frac{1}{2}}}{\delta_{0}^{\frac{1}{2}(n-p-q)+a_{0}+1} \delta_{1}^{\frac{1}{2} q+a_{1}+1}} \exp \left(-\frac{2 b_{0}+S S E}{2 \delta_{0}}-\frac{b_{1}}{\delta_{1}}\right)
$$

The result is immediate. Part (b) follows from the fact that $\left|R_{2}\right| \geq \delta_{1}^{-q}|B|$.

Corollary 2. (a) Assume that $\left(X_{1}^{\prime} X_{1}\right)^{-1}$ exists. Then the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ is proper under Model 1A.
(b) Assume that $\left(X^{\prime} X\right)^{-1}$ exists. Then the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ exists under Model 1 or Model 2 when $\rho=1 / \lambda_{1}$ or $\rho=1 / \lambda_{q}$.

This corollary follows from Corollary 1. A related result has appeared in Hobert \& Casella (1996) for the special case where rank $\left(X_{1}\right)=p$ and $B$ is a diagonal matrix with unknown elements. In this case $\Gamma \operatorname{rank}\left(R_{2}\right)=q$. If $\Gamma$ however $\Gamma B$ is not positive definite $\Gamma$ the posterior distribution may not be proper $\Gamma$ as shown in the following theorem.

Theorem 3. Assume that rank $\left(X_{1}\right)=p$ and rank $\left(X_{2}^{\prime} R_{1} X_{2}+B\right)<q$. For any priors on $\delta_{0}$ and $\delta_{1}$, the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ does not exist.

Proof. Since rank $\left(X_{1}\right)=p \Gamma(13)$ still holds. Since rank $\left(X_{2}^{\prime} R_{1} X_{2}+B\right)<q$ โfor any fixed $\delta_{0}$ and $\delta_{1} \Gamma$

$$
\int_{\mathbb{R}^{q}} \exp \left\{-\frac{(Z-\hat{Z})^{\prime} X_{2}^{\prime} R_{1} X_{2}(Z-\hat{Z})}{2 \delta_{0}}-\frac{Z^{\prime} B Z}{2 \delta_{1}}\right\} d Z=\infty
$$

This proves the result.

We note that if $B$ is positive definite our model reduces to that of Hobert \& Casella (1996) Twho provide necessary and sufficient conditions for the posterior distribution to be proper. Our result is an interesting extension to the situation where $B$ is not positive definite「as is often the case with the CAR(1) model.

One implication of our results is that Tamong the assumptions of Theorem 2 Trank $\left(X_{2}^{\prime} R_{1} X_{2}+B\right)=q$ is both necessary and sufficient for the posterior distribution of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ given $V$ to be proper. We illustrate the point by a simple example for which the posterior distribution may or may not be proper.

Example 1. Consider a balanced one-way analysis of variance $\Gamma$

$$
Y_{i j}=\theta+Z_{i}+e_{i j}, \quad i=1, \cdots, q ; \quad j=1, \cdots, m
$$

Here $\theta$ is the fixed effect $\Gamma Z=\left(Z_{1}, \cdots, Z_{q}\right)^{\prime}$ is the random effect $\Gamma$ and the $e_{i j}$ are independently and identically $N\left(0, \delta_{0}\right)$ distributed. This is a special case of (9) with $X_{1}=1_{q m}$ (a vector of ones) and $X_{2}=I_{q} \otimes 1_{m}$. Assume the prior (10). Clearly $\Gamma$ $X_{2}^{\prime} R_{1} X_{2}=r\left(I_{q}-\frac{1}{q} 1_{q} 1_{q}^{\prime}\right)$.

Case 1. $B=I_{q}$. For a proper prior on $\delta_{i}$ given in (11) Гthe posterior of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ is proper.

Case 2. $B=D-C$, a special case of Model 1 A . Since $1_{q}^{\prime} B 1_{q}=0$ एwe know that the rank of $X_{2}^{\prime} R_{1} X_{2}+B$ is $q-1$. From Theorem $3 \Gamma$ we know that for any proper prior on $\delta_{i}$ Гthe joint posterior of $\left(\theta, Z, \delta_{0}, \delta_{1}\right)$ does not exist.

Case 3. $B=I_{q}-\rho C$ Гwith the limiting case $\rho=1 / \lambda_{1}$ or $\rho=1 / \lambda_{q}$. This case is quite complicated. We study a simple case with $q=3$. Assume that $C=1_{3} 1_{3}^{\prime}-I_{3} \Gamma$ whose eigenvalues are $-1,-1,2$. If $\rho=1 / \lambda_{1}=-1 \Gamma$ then the rank of $X_{2}^{\prime} R_{1} X_{2}+B$ is $q=3$. Then the posterior distribution might be proper. On the other hand $\Gamma$ if $\rho=1 / \lambda_{3}=0.5$ then $1_{q}^{\prime} B 1_{q}=0 \Gamma$ and the posterior distribution does not exist. We
now change $C$ to

$$
C=\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 1 \\
0 & 1 & 0
\end{array}\right),
$$

whose eigenvalues are $-\sqrt{ } 2,0, \sqrt{ } 2$. By numerical calculation Twhen either $\rho=-1 / \sqrt{ } 2$ or $1 / \sqrt{ } 2 \Gamma$ the rank of $X_{2}^{\prime} R_{1} X_{2}+B$ is $q=3$. Consequently $\Gamma$ the posterior distribution would be proper for any proper prior of $\delta_{i}$.

### 3.2. Propriety of the posterior for a generalised linear mixed model

Consider the hierarchical model where $Y_{1}, Y_{2}, \cdots, Y_{N}$ are conditionally independent given parameters $V=\left(V_{1}, V_{2}, \cdots, V_{N}\right) \Gamma$ and $V_{i}$ follows the hierarchical prior defined by (9)-(11). Let $f_{i}\left(Y_{i} \mid V_{i}\right)$ be the distribution of $Y_{i}$ given $V_{i}$.

Theorem 4. Suppose there exist $Y_{i_{1}}, \cdots, Y_{i_{n}}\left(1 \leq i_{1}<\cdots<i_{n} \leq N ; p+q \leq\right.$ $n \leq N)$ such that

$$
\begin{equation*}
\int f_{j}\left(Y_{j} \mid V_{j}\right) d V_{j}<\infty, j \in\left\{i_{1}, \cdots, i_{n}\right\} \quad \text { and } \quad f_{j}\left(Y_{j} \mid V_{j}\right) \leq M, j \notin\left\{i_{1}, \cdots, i_{n}\right\} \tag{16}
\end{equation*}
$$

for some constant $M$, the corresponding design matrix $X_{1}^{*}=\left(x_{1, i_{1}}, \cdots, x_{1, i_{n}}\right)^{\prime}$ has full rank, and $X_{2}^{*}=\left(x_{2, i_{1}}, \cdots, x_{2, i_{n}}\right)^{\prime}$ has the same rank as the matrix $\left(x_{2,1}, \cdots, x_{2, N}\right)^{\prime}$. For any proper prior on $\delta_{i}$, the posterior distribution of $\left(V, \theta, Z, \delta_{0}, \delta_{1}\right)$ given $Y=$ $\left(Y_{1}, \cdots, Y_{N}\right)$ exists.

Proof. Without loss of generality assume that $i_{j}=j, j=1, \cdots, n$. Let $V^{*}=\left(V_{1}, \cdots, V_{n}\right)$. The posterior density of $\left(V, \theta, Z, \delta_{0}, \delta_{1}\right)$ given $Y$ is
$p\left(V, \theta, Z, \delta_{0}, \delta_{1} \mid Y\right) \propto \prod_{i=1}^{N} f_{i}\left(Y_{i} \mid V_{i}\right) \delta_{0}^{-\frac{1}{2}(N-n)} \prod_{i=n+1}^{N} \exp \left[-\frac{1}{2 \delta_{0}}\left(V_{i}-x_{1 i}^{\prime} \theta-x_{2 i}^{\prime} Z\right)^{2}\right] G^{*}$.

Here $G^{*}$ is defined by (12) with $X_{1}$ and $X_{2}$ being replaced by $X_{1}^{*}$ and $X_{2}^{*}$ Гrespectively. Using the second inequality in (16) and integrating with respect to $V_{n+1}, \cdots, V_{N}$ Twe obtain

$$
p\left(V^{*}, \theta, Z, \delta_{0}, \delta_{1} \mid Y\right) \propto \prod_{i=1}^{n} f_{i}\left(Y_{i} \mid V_{i}\right) G^{*}
$$

From the same argument as in the proof of Theorem 2Twe obtain

$$
p\left(V^{*}, \delta_{0}, \delta_{1} \mid Y\right) \propto \prod_{i=1}^{n} f_{i}\left(Y_{i} \mid V_{i}\right) \frac{\delta_{0}^{\frac{1}{2} q}+\delta_{1}^{\frac{1}{2} q}}{\delta_{0}^{\frac{1}{2}(n-p)+a_{0}+1} \delta_{1}^{\frac{1}{2} q+a_{1}+1}} \exp \left\{-\frac{2 b_{0}}{2 \delta_{0}}-\frac{b_{1}}{\delta_{1}}\right\}
$$

Clearly $\Gamma p\left(V^{*} \mid Y\right) \propto \prod_{i=1}^{n} f_{i}\left(Y_{i} \mid V_{i}\right)$, which is proper by the first inequality in (16).
In the original example given in $\S 1 \Gamma f_{i}\left(Y_{i} \mid V_{i}\right)$ is Poisson with mean $\mu_{i}=m_{i} e^{V_{i}} \Gamma$ where $V_{i}$ has the linear structure (9). Then $\Gamma f_{i}\left(Y_{i} \mid V_{i}\right)$ is bounded for any $Y_{i} \geq 0$ and

$$
\int f_{i}\left(Y_{i} \mid V_{i}\right) d V_{i}=\int_{0}^{\infty} \frac{e^{-\mu_{i}} \mu_{i}^{Y_{i}-1}}{Y_{i}!} d \mu_{i}
$$

which is finite for $Y_{i}>0$. For another example ${ }^{\text {. }}$ et $Y_{i} \mid V_{i}$ be binomial with parameter $m_{i}$ and $p_{i}=e^{V_{i}} /\left(e^{V_{i}}+1\right)$ एwhere $V_{i}$ has prior (9). Then $f_{i}\left(Y_{i} \mid V_{i}\right)$ is bounded in $V_{i}$ for any $0 \leq Y_{i} \leq m_{i}$ Гand

$$
\int_{-\infty}^{\infty} f_{i}\left(Y_{i} \mid V_{i}\right) d V_{i}=\int_{-\infty}^{\infty} \frac{e^{V_{i} Y_{i}}}{\left(e^{V_{i}}+1\right)^{m_{i}}} d V_{i}=\int_{0}^{1} p_{i}^{Y_{i}-1}\left(1-p_{i}\right)^{m_{i}-Y_{i}-1} d p_{i}
$$

which is finite if and only if $0<Y_{i}<m_{i}$.

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